

1/16

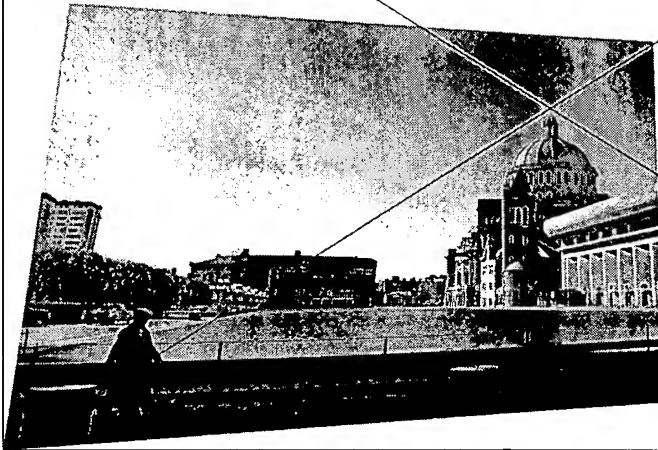


Fig. 1

2/16

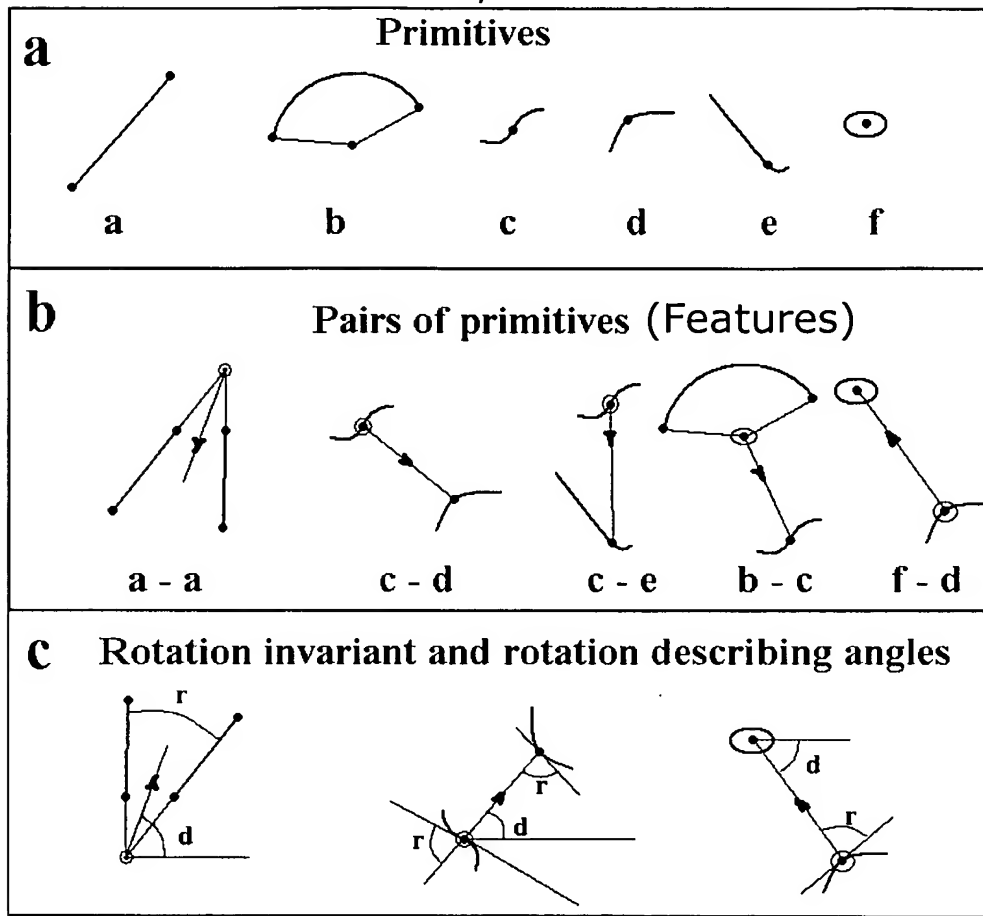


Fig. 2

3/16

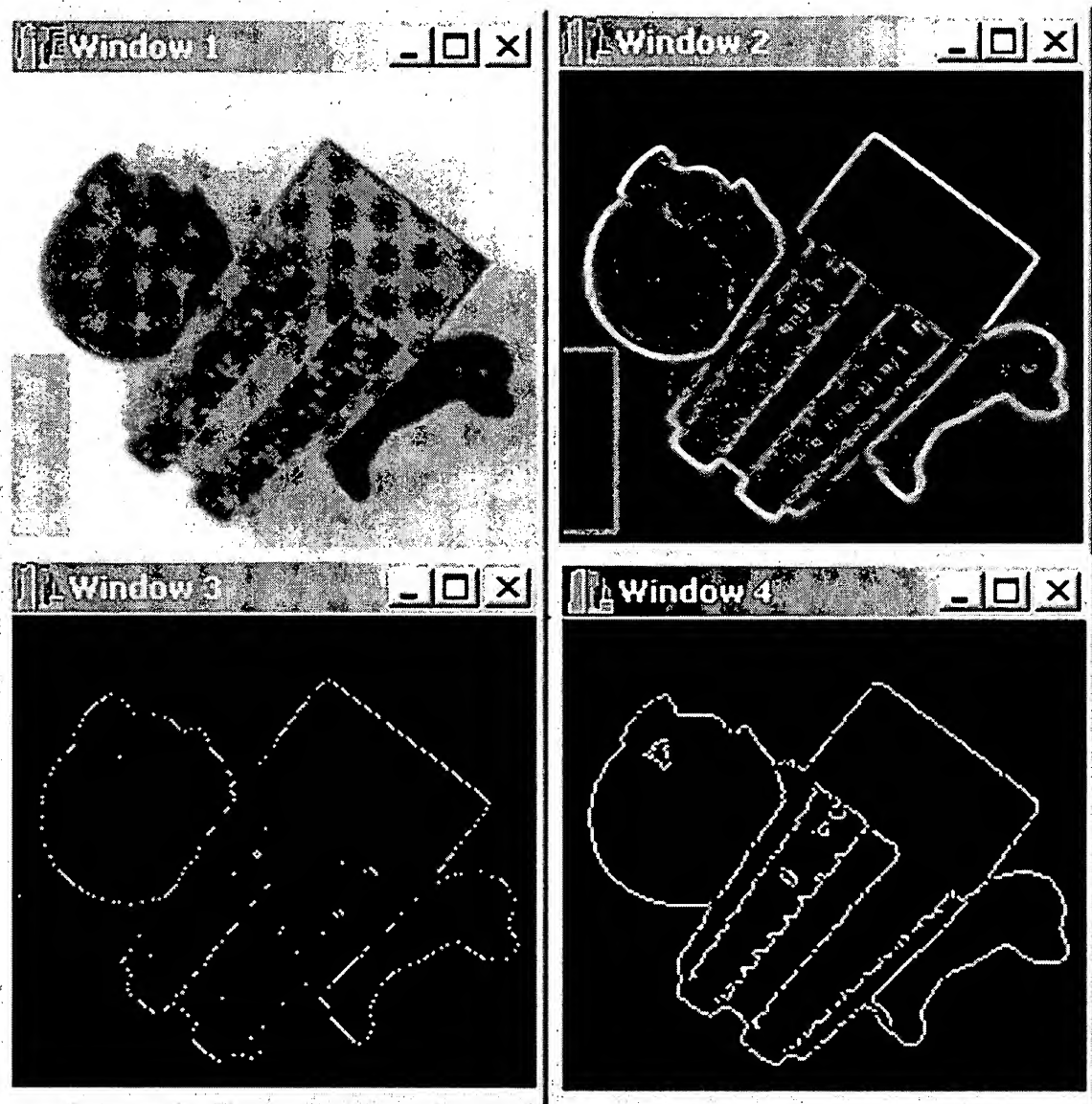


Fig. 3

4/16

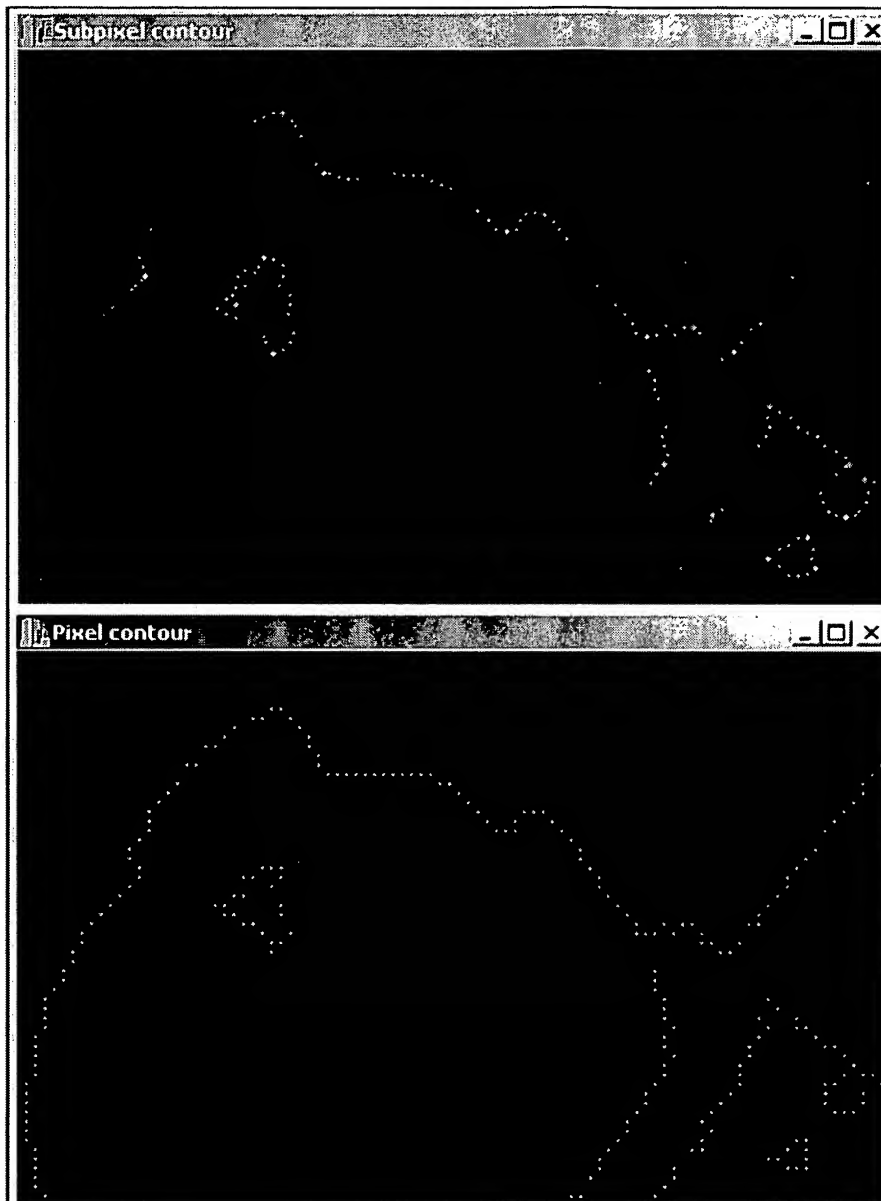


Fig. 4

5/16

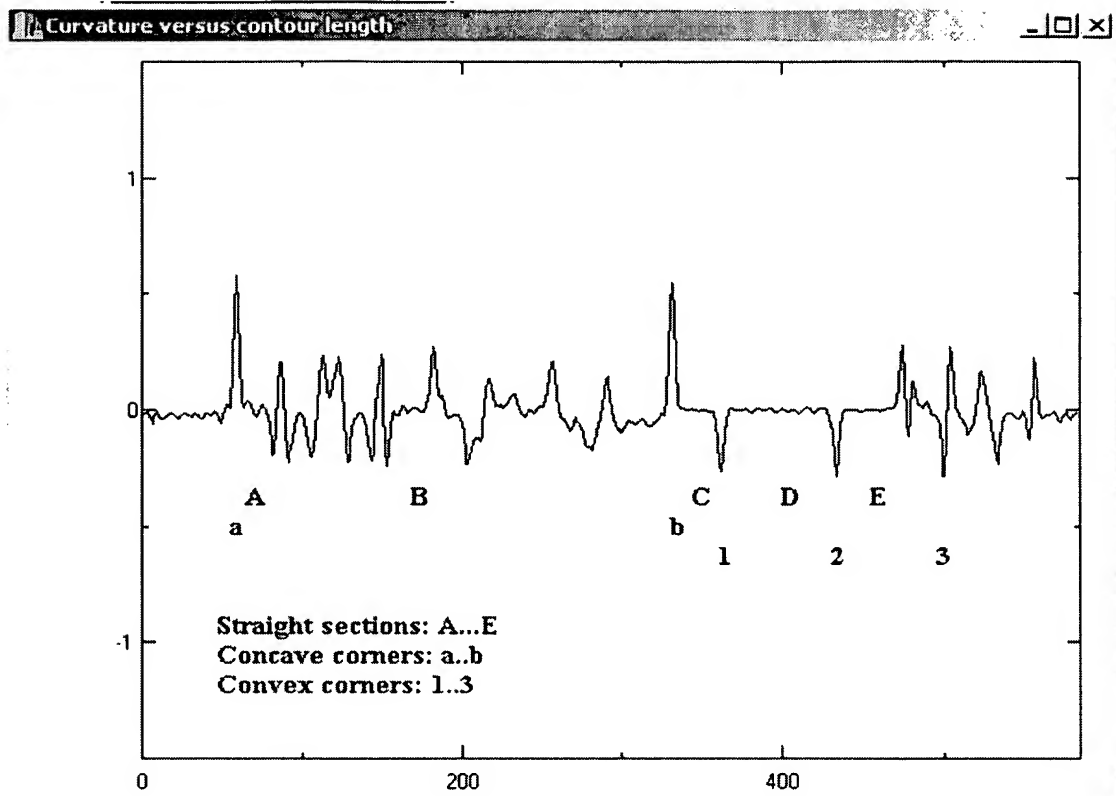


Fig. 5

6/16

Fig. 6

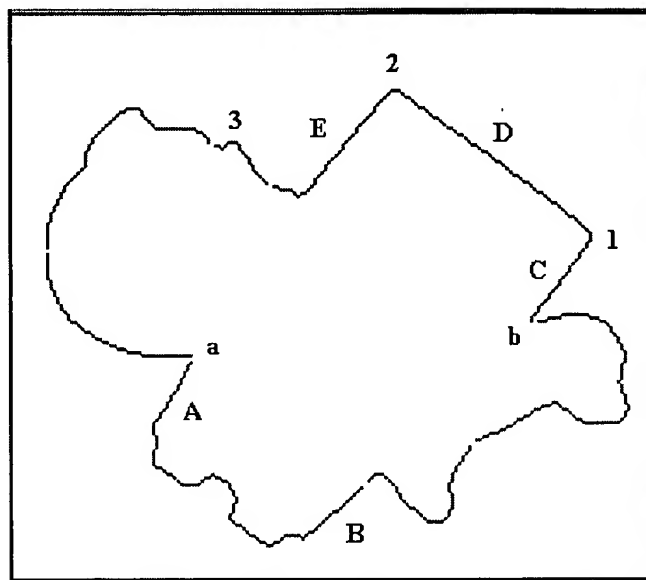
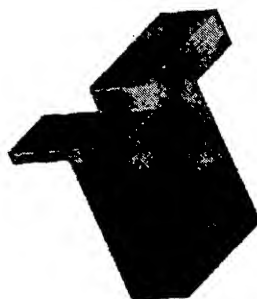


Fig. 7



7/16

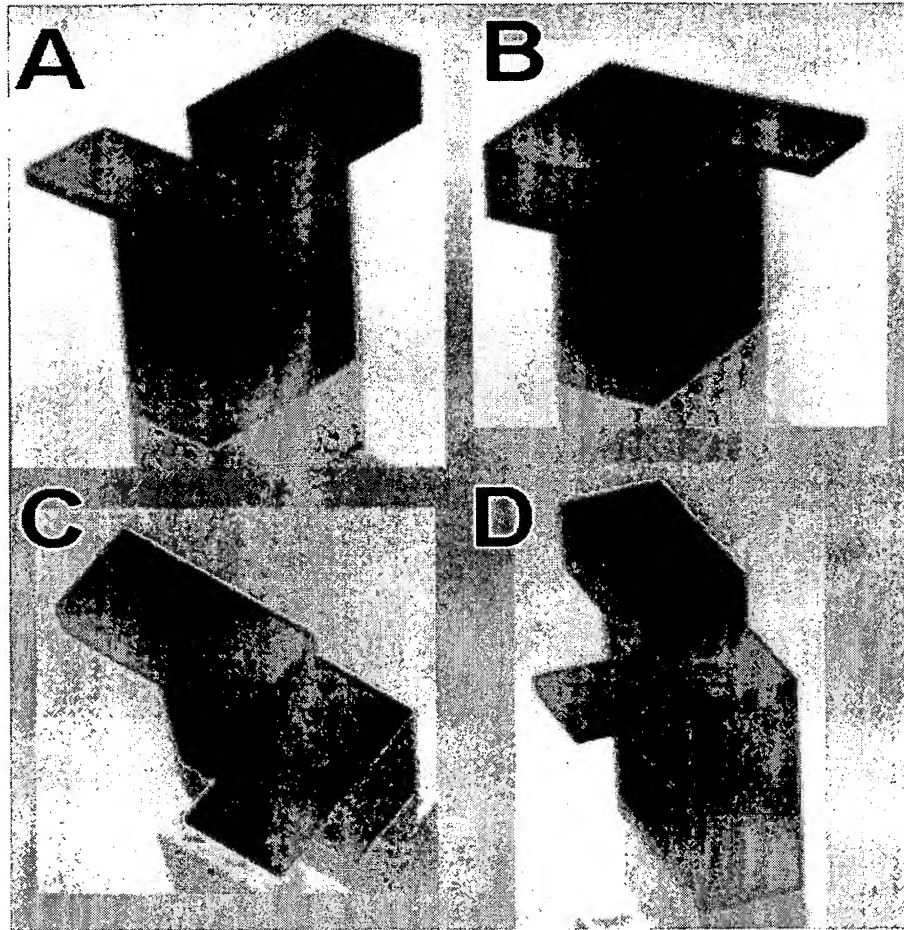


Fig. 8

8/16

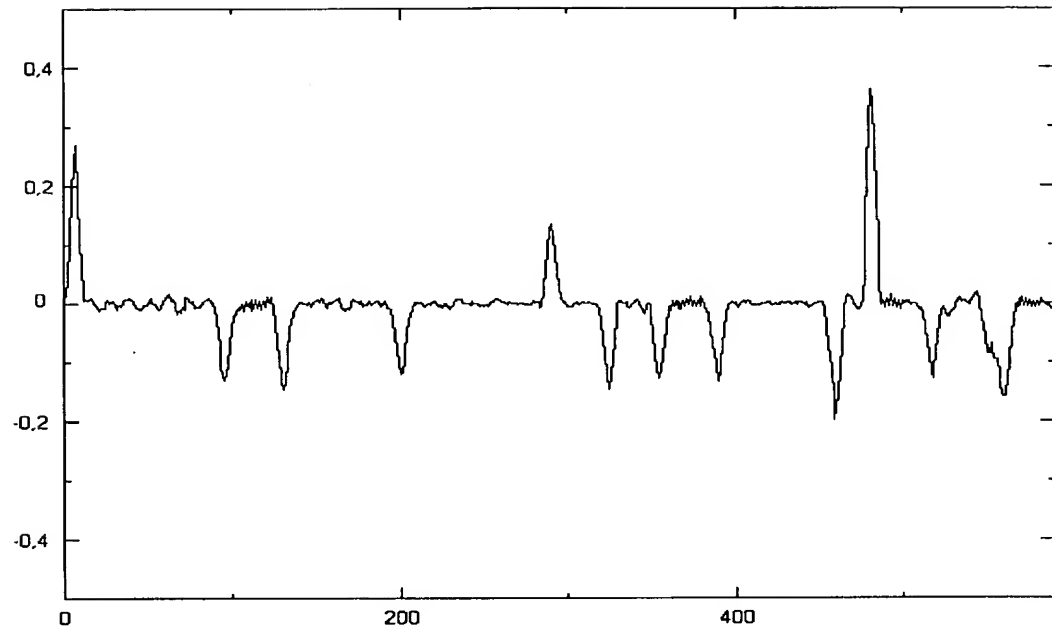


Fig. 9

9/16

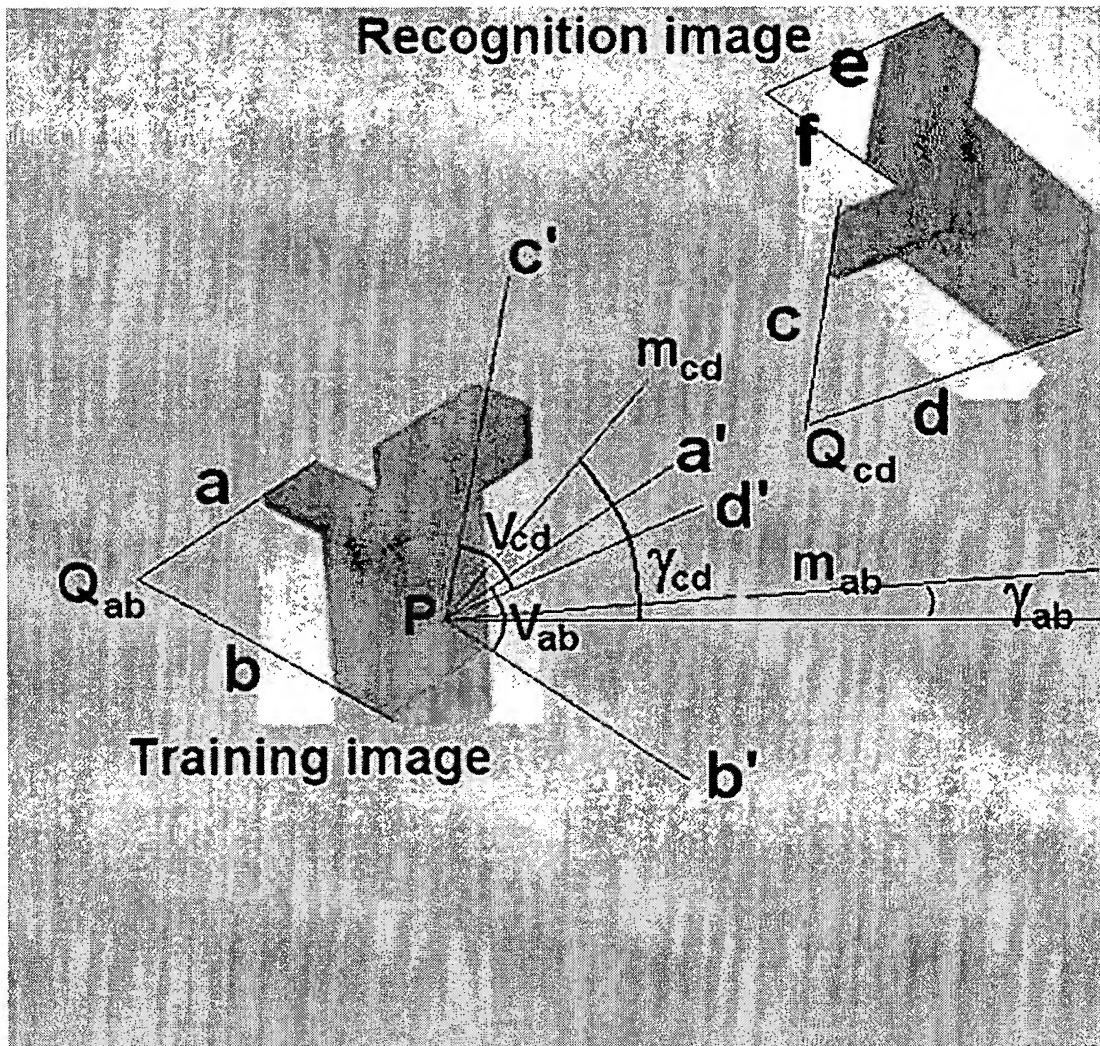


Fig. 10

10/16 Training flow chart

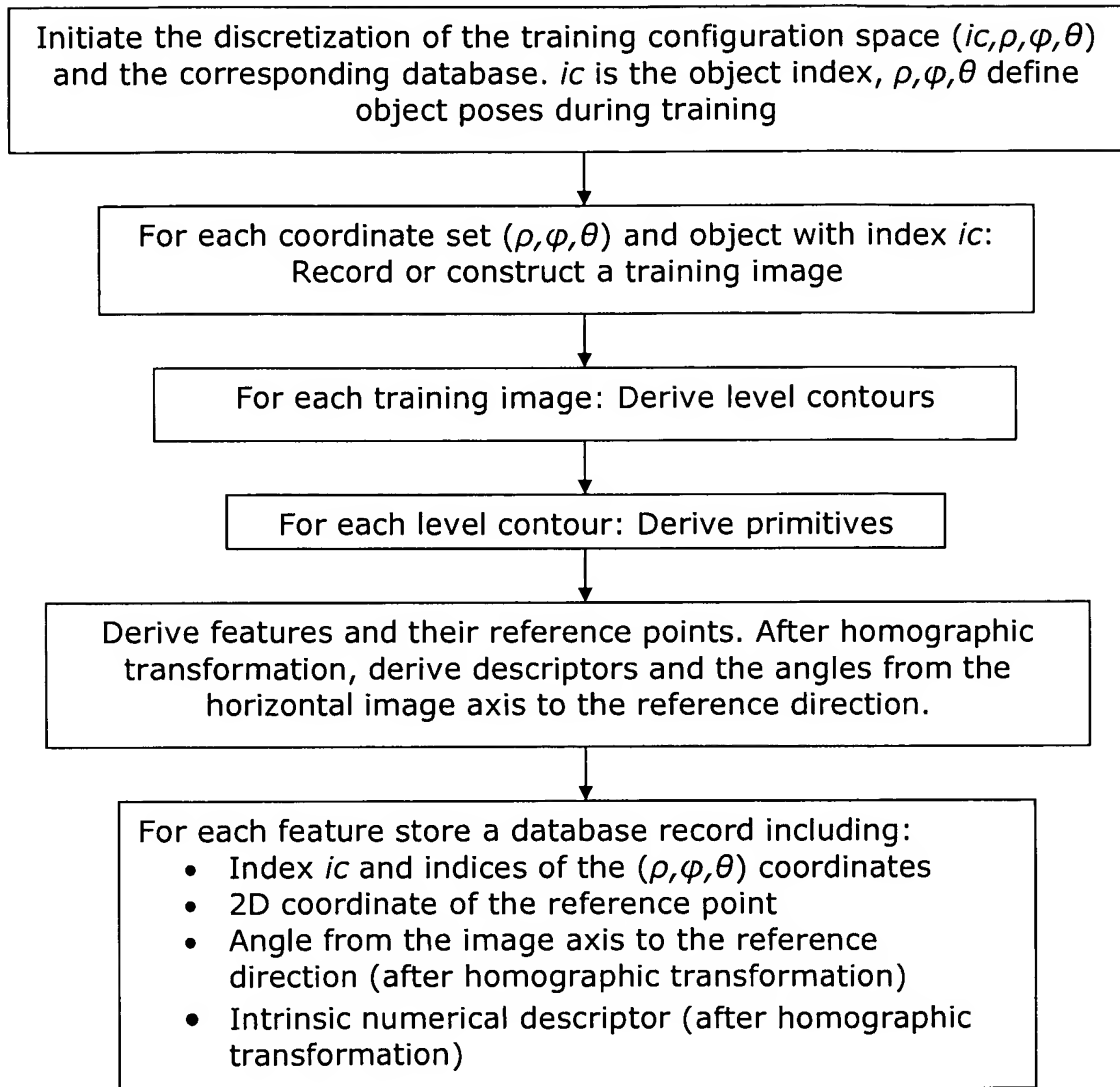
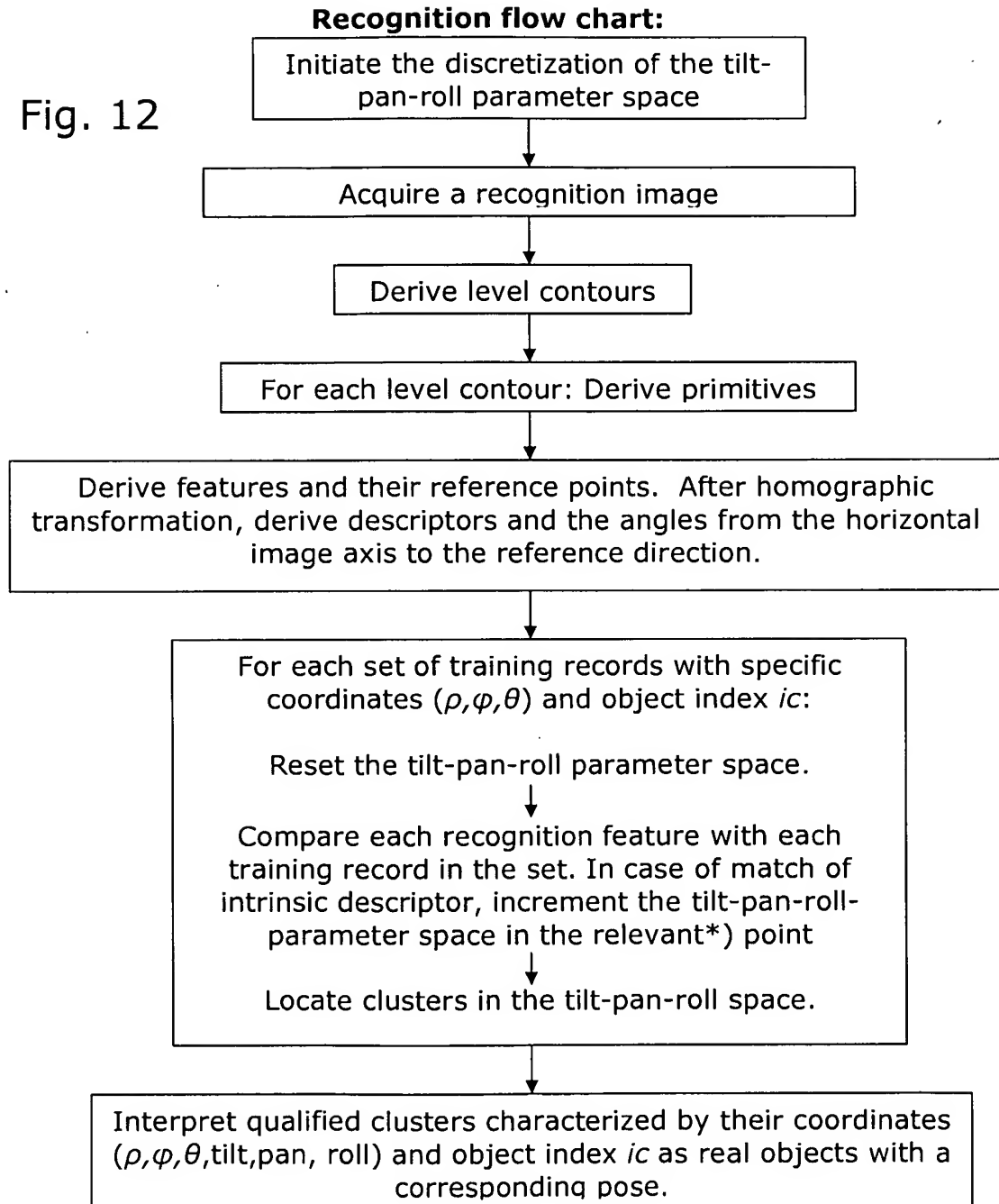


Fig. 11

Fig. 12



*) The (tilt, pan, roll) define the angular offset between the potential recognition pose and the actual training pose. This coordinate set is derived using the reference points and reference directions of both training and recognition features, see Appendix A

Fig. 13

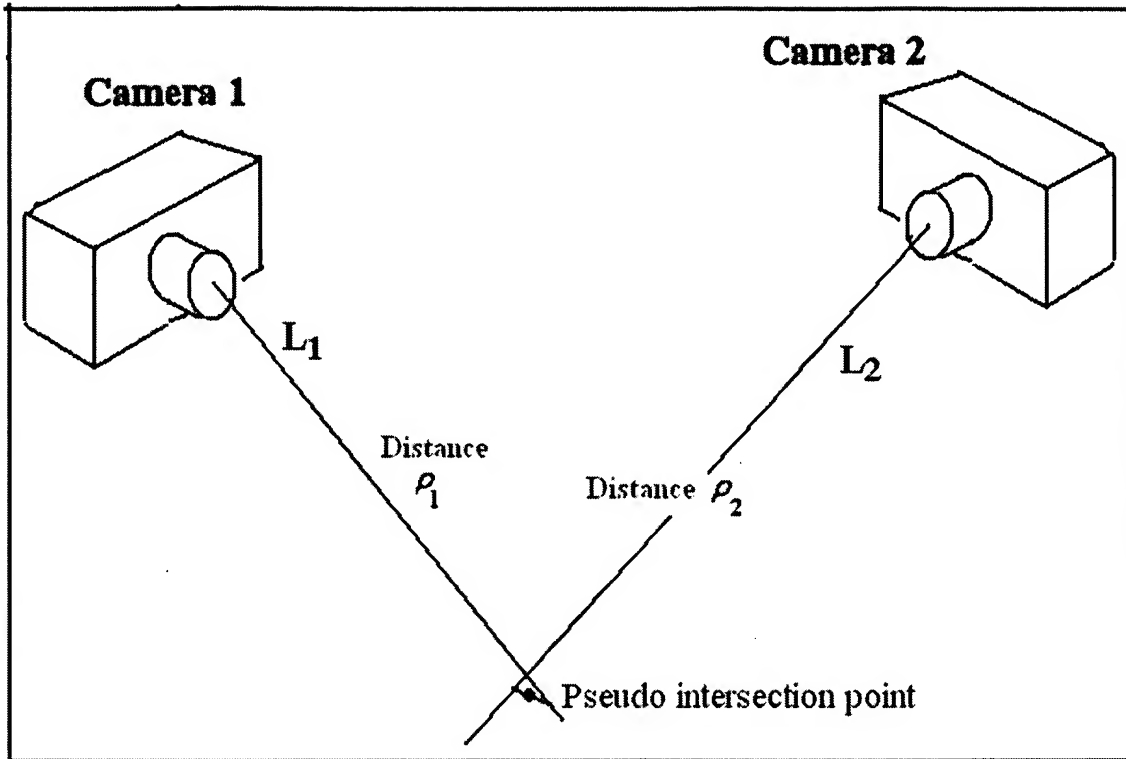
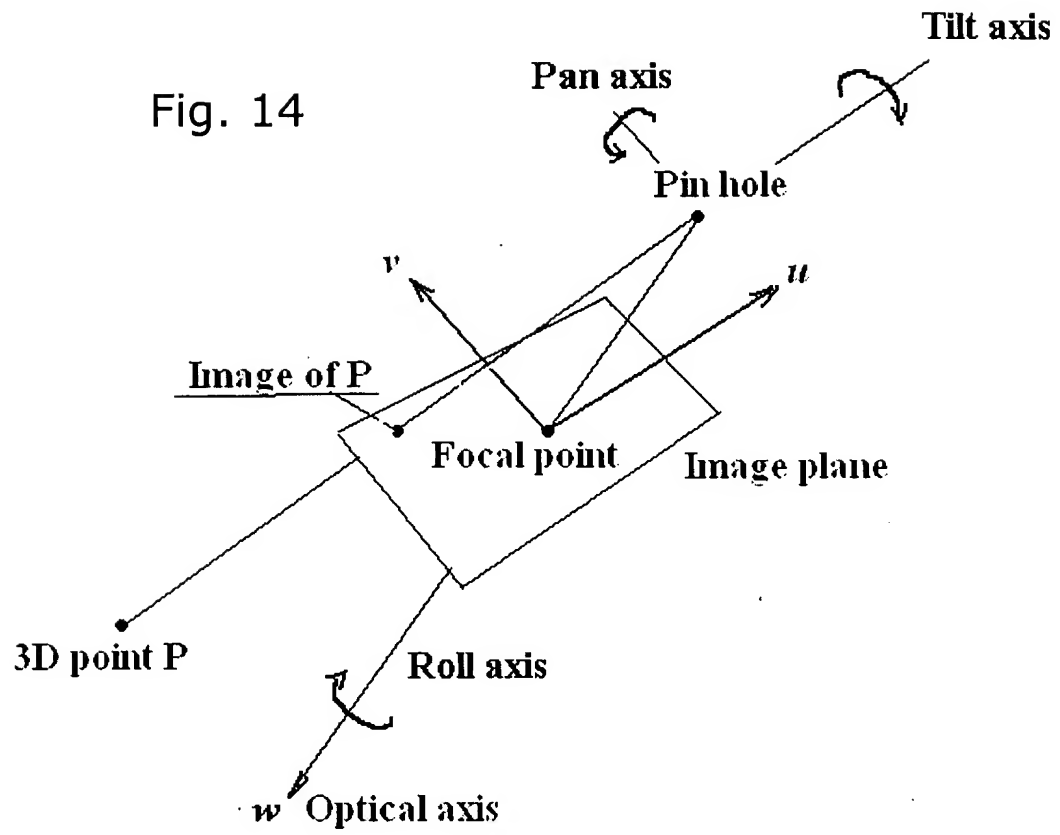


Fig. 14



14/16

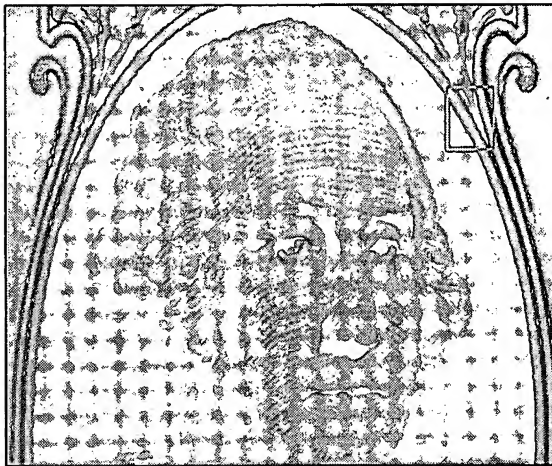


Fig. 15a

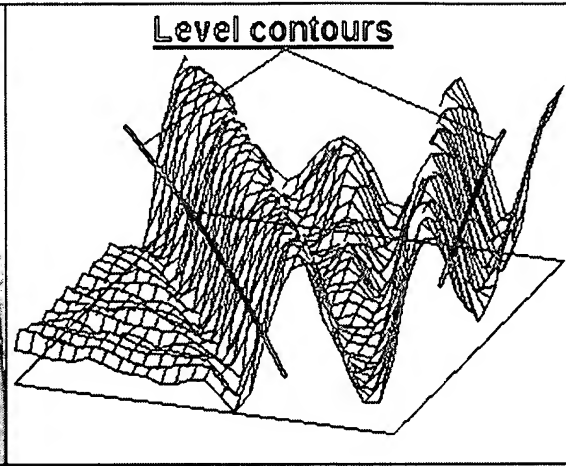
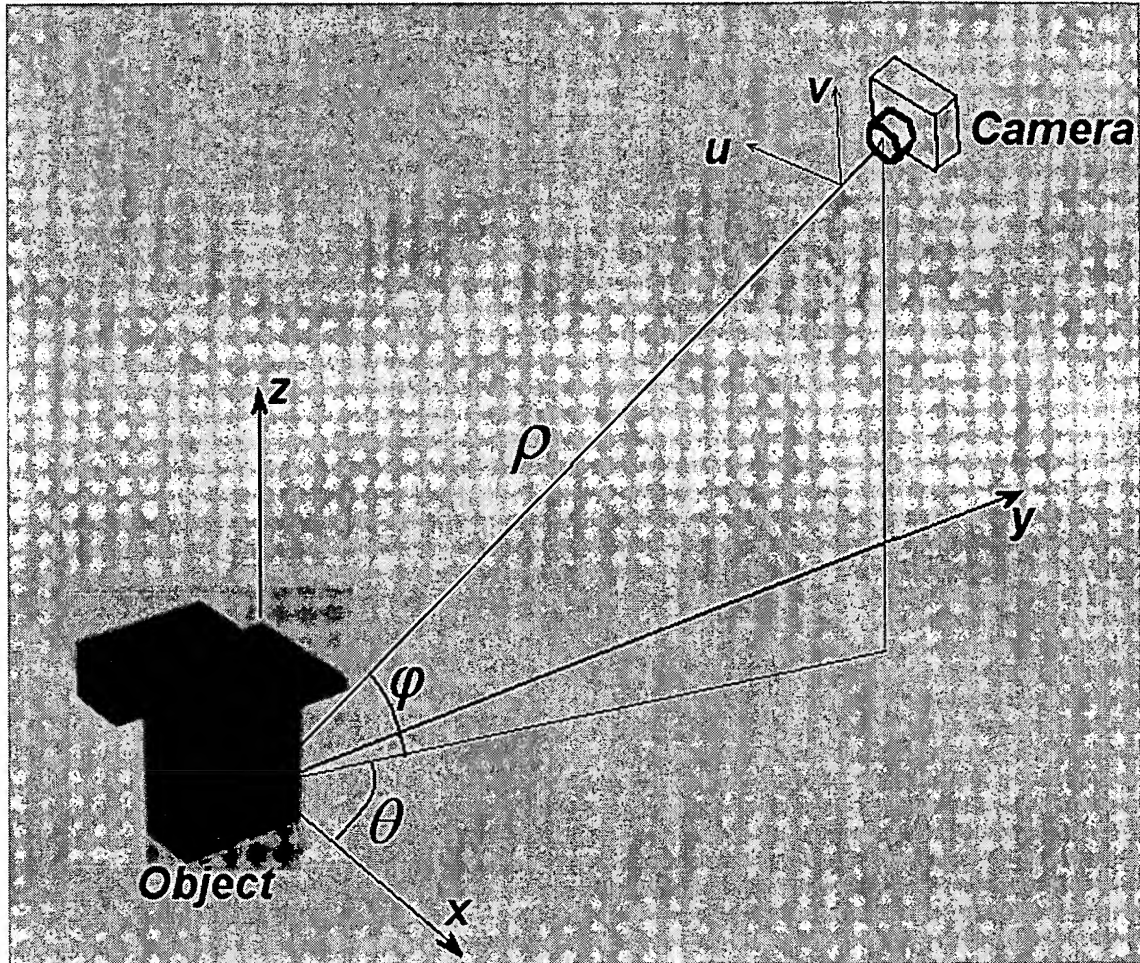


Fig. 15b

Fig. 15

15/16

Fig. 16



[illegible]